

University of Macau
Faculty of Science and Technology
Department of Electrical and Computer Engineering

Part A: Course Outline

Course Title:	Control Systems I		
Course Code:	ELEC 313	Year of Study:	3
Course Mode:	Theoretical with substantial laboratory/ practice content		
Compulsory/Elective:	Compulsory		
Course Prerequisites:	ELEC 261		
Prerequisite Knowledge	Signals and Systems, Mathematical Modeling, Differential Equations and Complex Variables		
Class/Laboratory Schedule:	Theory class: 4 hours; Tutorial/Practice class: 2 hours (per week)		
Duration	One semester	Credit Units	4.5
Text Books and References:	<p>[1] "Modern Control Systems," R.C. Dorf and R.H. Bishop, 12th ed., Prentice-Hall, 2010.</p> <p>[2] "Feedback Control of Dynamic Systems," G.F. Franklin, J.D. Powell and A. Emami-Naeini, 6th ed., Prentice-Hall, 2009.</p> <p>[3] "Modern Control Engineering," K. Ogata, 5th ed., Prentice-Hall, 2009.</p> <p>[4] "Modern Control Systems Analysis and Design Using Matlab and Simulink," R.H. Bishop, 7th ed., Addison Wesley, 1997.</p>		
Course Description:	<p>This is an introductory course on classical feedback control theory. It provides basic concepts and principles of system modeling, analysis and controller design for linear time-invariant systems using classical techniques including roots locus method and frequency response method. Laboratory experiments are designed so that the theory learnt in the class can be applied to real physical systems, and MATLAB CAD tools are introduced as an integral part of this course.</p>		
Topics Covered	<ol style="list-style-type: none"> 1. Basic concepts, history and examples of control systems; 2. Modeling of physical systems, system representations; 3. Laplace transform and transfer function analysis, system responses, stability analysis of linear systems; 4. Feedback control systems, characteristics and performance of control systems; 5. Root locus method and its applications; 6. Frequency method and its applications, stability from frequency responses; 7. Control system design and simulation using Matlab/Simulink and Control Toolbox. 		
Course Objectives:	<ol style="list-style-type: none"> 1. Introduce to students some real systems, which use automatic control. [k] 2. Introduce to students mathematical modeling of physical systems. [a, b, e] 3. Introduce students to analysis of feedback control systems. [a, c, e] 4. Introduce students to design of feedback control systems. [a, b, c, e, k] 5. Learning to apply course material to improve thinking, problem solving, and making. [b, e] 		

Course Assessment:	Assignments : 15% Quiz :15% Lab Experiments: 15% Mid-term Exam: 15% Final Exam: 40%																							
Relationship to Program Objectives and Outcomes	This course primarily contributes to EEE program outcomes that develop students abilities to: a. Ability to apply knowledge of mathematics, science and engineering. c. Ability to design a system, component or process to meet desired needs. This course secondarily contributes to EEE program outcomes that develop students abilities to: b. Ability to design and conduct experiments. e. Ability to identify, formulate and solve engineering problems. k. Ability to use the techniques, skills and modern engineering tools necessary for engineering practice.																							
Course Contents and Relationship to Program Criteria:	<table border="1"> <thead> <tr> <th>Week no.</th> <th>Topics</th> <th>Program Criteria</th> </tr> </thead> <tbody> <tr> <td>1</td> <td>Introduction Basic concepts, history and examples of control systems</td> <td>CS, ES</td> </tr> <tr> <td>3</td> <td>System Modeling and Representations Basic concepts of modeling, first principle modeling of typical systems, block diagram, signal flow graph, Mason's Law</td> <td>DIC, ES, DE, CV</td> </tr> <tr> <td>2</td> <td>System Analysis System responses, transfer function analysis, stability analysis, Routh-Hurwitz criterion</td> <td>DIC, ES, DE, CV</td> </tr> <tr> <td>2</td> <td>Root Locus and Frequency Methods Basic concepts and principles of root locus method and its applications, frequency response plots, Nyquist criterion, gain and phase margins, Nichols chart</td> <td>DIC, ES, DE, CV</td> </tr> <tr> <td>4</td> <td>Feedback Control System Design and Analysis Feedback control systems: characteristics, design and performance analysis, compensator design (lead, lag, lead-lag, PID).</td> <td>DIC, CS, ES, DE, CV</td> </tr> <tr> <td>2</td> <td>Matlab CAD tools and Lab Experiments System dynamics, control system design and performance analysis</td> <td>ES, CS</td> </tr> </tbody> </table>			Week no.	Topics	Program Criteria	1	Introduction Basic concepts, history and examples of control systems	CS, ES	3	System Modeling and Representations Basic concepts of modeling, first principle modeling of typical systems, block diagram, signal flow graph, Mason's Law	DIC, ES, DE, CV	2	System Analysis System responses, transfer function analysis, stability analysis, Routh-Hurwitz criterion	DIC, ES, DE, CV	2	Root Locus and Frequency Methods Basic concepts and principles of root locus method and its applications, frequency response plots, Nyquist criterion, gain and phase margins, Nichols chart	DIC, ES, DE, CV	4	Feedback Control System Design and Analysis Feedback control systems: characteristics, design and performance analysis, compensator design (lead, lag, lead-lag, PID).	DIC, CS, ES, DE, CV	2	Matlab CAD tools and Lab Experiments System dynamics, control system design and performance analysis	ES, CS
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Contribution of Course to meet the professional component:	This course prepares students to work professionally in the area of control systems and control related fields. Students should be able to apply knowledge of mathematics and engineering, to the analysis and design of control systems to meet desired needs.																							
Course Instructor(s):	Dr. Feng Wan																							
Prepared by:	Dr. Feng Wan																							

Program Criteria Policy:

Course VS Program Criteria

Scale: 1 (Highest) to 4 (Lowest)

Course	PS	DIC	BS	CS	ES	DE	LA	CV	DM
Control Systems I		3	3	4	1	2		2	

Terms:

Probability and Statistics (PS), Differential and Integral Calculus (DIC), Basic Science (BS), Computer Science (CS), Engineering Science (ES), Differential Equation (DE), Linear Algebra (LA), Complex Variables (CV), Discrete Mathematics (DM)

Program Outcome Policy:

Course VS Course Outcomes

(H= Highly Related, S = Supportive, N = None)

Course	a	b	c	d	e	f	g	h	i	j	k	l
Control Systems I	H	S	H	S	H	N	N	N	N	N	H	S

The electrical and electronics engineering program outcomes are:

- a. Ability to apply knowledge of mathematics, science and engineering.
- b. Ability to design and conduct experiments.
- c. Ability to design a system, component or process to meet desired needs.
- d. Ability to function on multidisciplinary teams.
- e. Ability to identify, formulate and solve engineering problems.
- f. Understanding of professional and ethical responsibility.
- g. Ability to communicate effectively.
- h. Broad education necessary to understand the impact of engineering solutions in global and societal context.
- i. Recognition of the need for and an ability to engage in life-long learning.
- j. Knowledge of contemporary issues.
- k. Ability to use the techniques, skills and modern engineering tools necessary for engineering practice.
- l. Ability to use the computer/IT tools relevant to the discipline along with an understanding of their processes and limitations

Curriculum Detail

ELEC 313 Control Systems I

Timetabled work in hours per week			No of teaching weeks	Total hours	No /Duration of exam papers	Max marks available from:	
Lecturer	Tutor	Practice				Exams	Course
4	1	1	14	84	2/5 hours	60	40

Term: 5th

Hours			Percentage content of					
Lecturer	Lab/tut	Other	Maths	Basic Science	Engineering Science	Engineering Design and Synthesis	Complementary Studies	Computer Studies
56	14/14	0	20	10	20	30	10	10

Design Elements

% of Design Content	Design Content in Course Work	Design Project	Design Content in Laboratories
20%	X		X

Course Assessment Policy:

- There will be approximately 8 homework assignments.
- Homework is due one week after assignment unless otherwise noted, no late submission is accepted. Zero mark will be given when homework is copied. Possible revision of homework grades may be discussed with the grader within one week from the return of the marked homework.
- Approximately three quizzes will be held during the semester.
- One mid-term exam and one final exam will be given with 2 hours and 3 hours respectively.